



# NASA SDS Product Specification

## Level-2 Geocoded Single Look Complex

### L2\_GSLC

Rev B

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# 1 INTRODUCTION

## 1.1 Purpose of Description

This document provides a specification of the NASA-ISRO Synthetic Aperture Radar (NISAR) L-SAR Level-2 Geocoded Single Look Complex product to be generated by the NASA Science Data System (SDS) and provided to the Distributed Active Archive Center (DAAC). This data product is referenced by the short name L2\_GSLC.

## 1.2 Document Organization

Section 2 provides an overview of the product, including its purpose, and latency.

Section 3 provides the structure of the product, including granule definition, file organization, spatial resolution, temporal and spatial organization of the content, the size and data volume.

Section 4 provides qualitative descriptions of the information provided in the product.

Section 5 provides a detailed identification of the individual fields within the L2\_GSLC product, including for example their units, size, coordinates, etc.

Section 6 provides a description of the metadata cube representation.

Appendix A provides a listing of the acronyms used in this document.

Appendix B provides a description of geolocation grids and projection systems used for the product.

## 1.3 Applicable and Reference Documents

Applicable documents levy requirements on areas addressed in this document. Reference documents are cited to provide additional information to readers. In case of conflict between the applicable documents and this document, the Project shall review the conflict to find the most effective resolution.

### Applicable Documents

- [AD1] NISAR NASA SDS Level 4 Requirements, JPL D-95655, Initial, Sep. 13, 2019
- [AD2] NISAR NASA SDS Algorithm Development Plan, JPL D-95678, Initial, Sep. 12, 2019
- [AD3] NISAR Science Data Management and Archive Plan, JPL D-80828, June 1, 2016
- [AD4] NISAR Science Management Plan, JPL D-76340, Rev A, Aug. 14, 2018
- [AD5] NISAR Calibration and Validation Plan, JPL D-102256, September. 2019
- [AD6] NISAR NASA SDS L4 Software Management Plan (SMP), JPL D-95656, Rev A, Sep. 19, 2019
- [AD7] ISO-19115-2, <https://www.iso.org/obp/ui/#iso:std:iso:19115:-2:ed-2:v1:en>



## Reference Documents

- [RD1] NISAR NASA SDS Algorithm Theoretical Basis Document, JPL D-95677, Oct. 6, 2022.
- [RD2] EOSDIS Handbook, July 2016, retrieved from <https://cdn.earthdata.nasa.gov/conduit/upload/5980/EOSDISHandbookWebFinal2.pdf>
- [RD3] NISAR SDS File Naming Conventions, JPL D-102255, Initial, Nov. 4, 2020
- [RD4] NISAR L1\_RSLC Product Specification Document, JPL D-102268, R3.3, May 15, 2023
- [RD5] HDF5 documentation at <https://portal.hdfgroup.org/display/HDF5/HDF5>
- [RD6] Eineder, M. (2003), Efficient simulation of SAR interferograms of large areas and of rugged terrain, IEEE Transactions on Geoscience and Remote Sensing, 41(6), 1415-1427.

The NISAR Level 1 science requirements are translated into requirements on the various spacecraft and instrument systems, including the requirements related to the processing system producing the L0-L2 products. These SDS requirements [AD1] fall into three general categories: resolution requirements, radiometric and spatial location accuracy requirements, and latency and throughput requirements.

## 2 PRODUCT OVERVIEW

### 2.1 Product Background

Each NASA SDS L0-L2 LSAR product (Figure 2-1 and Table 2-1 Product Dependency) is distributed as a single Hierarchical Data Format version 5 (HDF5, [RD5]) granule. All the metadata and imagery data are packaged in clearly defined sub-groups within the granule in compliance with the HDF5 specification.

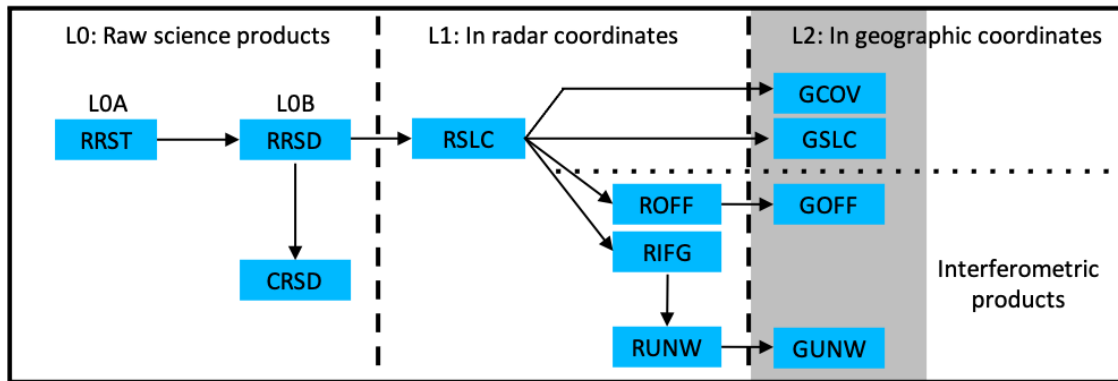


Figure 2-1 Product Dependency

Table 2-1. Key to Product Dependency Diagram

Product	Scope	Description	Granule Size
Radar Raw Science Telemetry (RRST)	Global	This LOA product is the raw downlinked data delivered to SDS	By downlinked files
Radar Raw Signal Data (RRSD)	Global	This LOB product is corrected, aligned radar pulse data derived from the RRST products and used for further processing	By radar observation, i.e., continuous data collected in a single radar mode
Calibration Raw Signal Data (CRSD)	Global	This LOB product contains instrument calibration data.	By radar datatake, i.e., a sequence of observations for one radar-on period

Product	Scope	Description	Granule Size
Range-Doppler Single Look Complex (RSLC)	Global	Used to generate all higher-level products	On pre-defined track/frame. High-resolution modes will have a high-res RSLC product and a background resolution RSLC product
Range-Doppler Nearest-Time Interferogram (RIFG)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co-pol channels only.	Multi-looked interferogram in Range Doppler coordinates with geometrical phase (including topographic phase) removed and formed using high-resolution dense pixel offsets.	On pre-defined track/frame
Range-Doppler Nearest-Time Pixel Offsets (ROFF)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co-pol channels only.	Unfiltered and unculled layers of pixel offsets in Range Doppler coordinates with different resolutions obtained from incoherent speckle tracking.	On pre-defined track/frame
Range-Doppler Nearest-Time Unwrapped Interferogram (RUNW)	Antarctica, Greenland, and selected mountain glaciers. Nearest pair in time and co-pol channels only.	Multi-looked, unwrapped differential interferogram in Range Doppler coordinates with geometrical phase (including topographic phase) removed.	On pre-defined track/frame

Product	Scope	Description	Granule Size
Geocoded SLC (GSLC)	Global and all channels.	Geocoded version of RSLC product using the MOE state vectors and a DEM.	On pre-defined track/frame
Geocoded Nearest-Time Pixel Offsets (GOFF)	Antarctica, Greenland, and mountain glaciers. Nearest pair in time and co-pol channels only.	Geocoded version of ROFF product using the MOE state vectors and a DEM.	On pre-defined track/frame

Product	Scope	Description	Granule Size
Geocoded Nearest-Time Unwrapped Interferogram (GUNW)	Global. Nearest pair in time and co-pol channels only.	Geocoded, multi-looked unwrapped differential interferogram with geometrical phase (including topographic phase) removed. It contains a geocoded version of the wrapped interferogram and normalized interferometric correlation at a finer posting.	On pre-defined track/frame
Geocoded Polarimetric Covariance Matrix (GCOV)	Global and all channels. Single/Dual/Quad pol.	Geocoded, multi-looked polarimetric covariance matrix.	On pre-defined track/frame

Table 2-2 NISAR Data Level Descriptions defined by Science.

Data Level	Description
Level 0A	Unprocessed instrument data with some communications artifacts removed, but without reconstruction of missing data and reordering of samples from the instrument. May still contain bit errors and missing data that needs reconstruction.
Level 0B	Reconstructed, unprocessed instrument data at original resolution, time ordered, all communications artifacts removed.
Level 1	Processed instrument data, focused to full resolution complex images, time referenced and annotated with ancillary information, including radiometric and relevant geometric calibration coefficients and georeferencing parameters (i.e. platform ephemeris) computed and appended, in natural radar coordinates.
Level 2 Category 1	Derived radar-specific parameters at the same or reduced resolution as Level 1 imagery, but resampled and geocoded to a geographic or ellipsoidal grid.
Level 2 Category 2	Derived radar-specific parameters at reduced resolution, in original Level 1 coordinates.
Level 3	Geophysical parameters derived from Level 1 or 2 data that have been spatially and/or temporally re-sampled to a global grid.

## 2.2 L2\_GSLC Overview

The L2\_GSLC product is a Level 2 Category 1 product derived from the L1\_RSLC product by geocoding the input RSLC into a geocoded map coordinate system such as UTM/ Polar stereographic system (Appendix B: Geocoded Product Grids). The geocoding is performed by inverse mapping of the map coordinates with their topographic heights into the radar coordinate system and interpolating the radar signal at the radar location corresponding to the map

coordinate. For more details about the geocoding algorithm please see the NISAR NASA SDS Algorithm Theoretical Basis Document (ATBD) [RD1].

The spacing of the L2\_GSLC product in East and North directions is comparable to the full resolution original L1\_RSLC product (Table 2-3).

Table 2-3 Posting of L2\_GSLC product based on imaging bandwidth

Range Bandwidth (MHz)	Ground Range Resolution Mid-Swath (m)	Posting in Northing (m)	Posting in Easting (m)
5	~38.5	5	40
20	~9.6	5	10
40	~4.8	5	5
80	~2.4	5	2.5

Phase preserving complex interpolation is used to project the data onto a uniformly spaced, north-south/east-west aligned geographic grid. The GSLC is flattened with respect to the orbit used in the RSLC processing, which eliminates the topographic phase contribution in the GSLC.

The L2\_GSLC product contains individual binary raster layers representing complex signal return for each polarization layer. The L2\_GSLC product contains lookup tables referenced to geographic coordinates instead of image coordinates. The L2\_GSLC product includes a mask layer indicating water bodies and shadow-layover.

The structure of the L2\_GSLC product is described in Section 4. The details of the data elements are given in Section 5. Metadata cubes are discussed in Section 6.

## 3 PRODUCT ORGANIZATION

### 3.1 File Format

All NISAR standard products are in the Hierarchical Data Format version 5 (HDF5, [RD5]). HDF5 is a general-purpose file format and programming library for storing scientific data. The National Center for Supercomputing Applications (NCSA) at the University of Illinois developed HDF to help scientists share data more easily. Use of the HDF library enables users to read HDF files regardless of the underlying computing environments. HDF files are equally accessible in Fortran, C/C++, and other high-level computation packages such as IDL, MATLAB, or Python.

The HDF Group, a spin-off organization of the NCSA, is responsible for development and maintenance of HDF. Users should reference The HDF Group website at <https://portal.hdfgroup.org/display/HDF5/HDF5> [RD5] to download HDF software and documentation.

HDF5 represents a significant departure from the conventions of previous versions of HDF. The changes that appear in HDF5 provide flexibility to overcome many of the limitations of previous releases. The basic building blocks have been largely redefined and are more powerful but less numerous. The key concepts of the HDF5 Abstract Data Model are Files, Groups, Datasets, Datatypes, Attributes and Property Lists. The following sections provide a brief description of each of these key HDF5 concepts.

#### 3.1.1 HDF5 File

A File is the abstract representation of a physical data file. Files are containers for HDF5 Objects. These Objects include Groups, Datasets, and Datatypes.

#### 3.1.2 HDF5 Group

Groups provide a means to organize the HDF5 Objects in HDF5 Files. Groups are containers for other Objects, including Datasets, named Datatypes and other Groups. In that sense, groups are analogous to directories that are used to categorize and classify files in standard operating systems.

The notation for files is identical to the notation used for Unix directories. The root Group is “/”. A Group contained in root might be called “/myGroup.” Like Unix directories, Objects appear in Groups through “links”. Thus, the same Object can simultaneously be in multiple Groups.

### 3.1.3 HDF5 Dataset

The Dataset is the HDF5 component that stores user data. Each Dataset associates with a Dataspace that describes the data dimensions, as well as a Datatype that describes the basic unit of storage element. A Dataset can also have Attributes.

### 3.1.4 HDF5 Datatype

A Datatype describes a unit of data storage for Datasets and Attributes. Datatypes are subdivided into Atomic and Composite Types.

Atomic Datatypes are analogous to simple basic types in most programming languages. HDF5 Atomic Datatypes include Time, Bitfield, String, Reference, Opaque, Integer, and Float. Each atomic type has a specific set of properties. Examples of the properties associated with Atomic Datatypes are:

- Integers are assigned size, precision, offset, pad byte order, and are designated as signed or unsigned.
- Strings can be fixed or variable length, and may or may not be null-terminated.
- References are constructs within HDF5 Files that point to other HDF5 Objects in the same file.

HDF5 provides a large set of predefined Atomic Datatypes. Table 3-1 lists the Atomic Datatypes that are used in NISAR data products.

Table 3-1. HDF5 Atomic Datatypes

HDF5 Atomic Datatypes	Description
H5T_STD_U8LE	unsigned, 8-bit, little-endian integer
H5T_STD_U16LE	unsigned, 16-bit, little-endian integer
H5T_STD_U32LE	unsigned, 32-bit, little-endian integer
H5T_STD_U64LE	unsigned, 64-bit, little-endian integer
H5T_STD_I8LE	signed, 8-bit, little-endian integer
H5T_STD_I16LE	signed, 16-bit, little-endian integer
H5T_STD_I32LE	signed, 32-bit, little-endian integer
H5T_STD_I64LE	Signed, 64-bit, little-endian integer
H5T_IEEE_F32LE	32-bit, little-endian, IEEE floating point
H5T_IEEE_F64LE	64-bit, little-endian, IEEE floating point
H5T_C_S1	character string made up of one or more bytes

Derived Datatypes are user-defined variants of predefined Atomic Datatypes where the data organization has been modified at the bit-level. Derived data types are particularly useful for representing custom N-bit integers and floating point numbers.

Composite Datatypes incorporate sets of Atomic datatypes. Composite Datatypes include Array, Enumeration, Variable Length and Compound.

- The Array Datatype defines a multi-dimensional array that can be accessed atomically.

- Variable Length presents a 1-D array element of variable length. Variable Length Datatypes are useful as building blocks of ragged arrays.
- Compound Datatypes are composed of named fields, each of which may be dissimilar Datatypes. Compound Datatypes are conceptually equivalent to structures in the C programming language.

Named Datatypes are explicitly stored as Objects within an HDF5 File. Named Datatypes provide a means to share Datatypes among Objects. Datatypes that are not explicitly stored as Named Datatypes are stored implicitly. They are stored separately for each Dataset or Attribute they describe.

NISAR products employ the following Derived and Compound Datatypes.

Table 3-2 NISAR HDF5 Derived and Compound Datatypes

Description	Comments
16-bit little-endian floating point	"binary16" half precision type in IEEE 754-2008 standard. Matches numpy.float16 type in Python. We will refer to this type as H5T_IEEE_F16LE or Float16 in our documents.
H5T_COMPOUND { 16-bit little-endian floating-point "r"; 16-bit little-endian floating-point "i"; }	Complex numbers made up of two half precision floating point numbers. We will refer to this type as H5T_CPX_F16LE or CFloat16 in our documents.
H5T_COMPOUND { 32-bit little-endian floating-point "r"; 32-bit little-endian floating-point "i"; }	Complex numbers made of two single precision floating point numbers. We will refer to this type as H5T_CPX_F32LE or CFloat32 in our documents.
H5T_COMPOUND { 64-bit little-endian floating-point "r"; 64-bit little-endian floating-point "i"; }	Complex numbers made of two double precision floating point numbers. We will refer to this type as H5T_CPX_F64LE or CFloat64 in our documents.

### 3.1.5 HDF5 Attribute

An Attribute is a small aggregate of data that describes Groups or Datasets. Like Datasets, Attributes are also associated with a particular Dataspace and Datatype. Attributes cannot be subsetted or extended. Attributes themselves cannot have Attributes.



## 3.2 NISAR File Organization

### 3.2.1 Groups

All NISAR HDF5 files are organized as groups with no actual data at the root("/") level. Table 3-3 shows the general layout of the HDF5 files that are generated by the NISAR Science Data System. All data are organized under "/science" with data from the L-SAR and S-SAR instruments separated into their own groups.

Table 3-3 Group organization at the top level of a NISAR HDF5 File

Group Name	Description
/science/LSAR	All science data from the L-SAR instrument is organized under this group
/science/SSAR	All science data from the S-SAR instrument is organized under this group
/science/[L S]SAR/identification	File level metadata for cataloging, archiving the particular granule

In the nominal baseline, L-SAR and S-SAR data will not appear in the same granule, even if they cover the same geographic area. The rest of the document from this point on describes the layout of the product containing L-SAR data.

### 3.2.2 File Level Metadata

Global metadata at the file level are currently given as Global Attributes shown in Table 3-4.

Metadata regarding the data in the particular granule are given in the "/science/LSAR/identification" Group. These data are described further in Sec 5.2.

Table 3-4 Global Attributes of L2\_GSLC

Attribute	Format	Description
Conventions	string	NetCDF-4 conventions adopted in this product. This attribute should be set to CF-1.8 to indicate that the group is compliant with the Climate and Forecast NetCDF conventions.
title	string	NISAR L2_GSLC Product
institution	string	Name of producing agency.
mission_name	string	"NISAR"
reference_document	string	Name and version of Product Description Document to use as reference for product.

contact	string	Contact information for producer of product. (e.g., "ops@jpl.nasa.gov").
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### 3.2.3 Variable Metadata (HDF5 Attributes)

NISAR standards incorporate additional metadata that describe each HDF5 Dataset within the HDF5 file. Each of these metadata elements appear in an HDF5 Attribute that is directly associated with the HDF5 Dataset. Wherever possible, these HDF5 Attributes employ names that conform to the Climate and Forecast (CF) conventions.

Table 3-5 lists the CF names for the HDF5 Attributes that NISAR products typically employ.

Table 3-5. Common variable attributes in HDF5 file.

Attribute	Description
_FillValue	The value used to represent missing or undefined data. (Before applying add_offset and scale_factor).
add_offset	If present this value should be added to each data element after it is read. If both scale_factor and add_offset attributes are present, the data are first scaled before the offset is added.
scale_factor	If present, the data are to be multiplied by the value after they are read. If both scale_factor and add_offset attributes are present, the data are first scaled before the offset is added.
comment	Miscellaneous information about the data or the methods to generate it.
coordinates	Coordinate variables associated with the variable. The basename of the coordinate variable is used in this representation and group scoping rules for CF conventions apply.
long_name	A descriptive variable name that indicates its content.
quality_flag	Names of variable quality flag(s) that are associated with this variable to indicate its quality.
units	Unit of data after applying offset (add_offset) and scale_factor.
valid_max	Maximum theoretical value of variable before applying scale_factor and add_offset (not necessarily the same as maximum value of actual data)
valid_min	Minimum theoretical value of variable before applying scale_factor and add_offset (not necessarily the same as minimum value of actual data)

Some HDF5 datasets are populated with statistical attributes. Table 3-6 and Table 3-7 describe statistical attributes added to real- and complex-valued HDF5 datasets, respectively. The list of real- and complex-valued HDF5 datasets for the standard GSLC product is given in Table 3-8.

Table 3-6. Statistical attributes for real-valued HDF5 datasets.

Attribute	Description
min_value	Minimum value of a real-valued HDF5 dataset
mean_value	Mean value of a real-valued HDF5 dataset
max_value	Maximum value of a real-valued HDF5 dataset

sample_standard_deviation	Sample standard deviation of a real-valued HDF5 dataset
---------------------------	---

Table 3-7. Statistical attributes for complex-valued HDF5 datasets.

Attribute	Description
min_real_value	Minimum value of the real part of a complex-valued HDF5 dataset
mean_real_value	Mean value of the real part of a complex-valued HDF5 dataset
max_real_value	Maximum value of the real part of a complex-valued HDF5 dataset
sample_standard_deviation_real	Sample standard deviation of the real part of a complex-valued HDF5 dataset
min_imag_value	Minimum value of the imaginary part of a complex-valued HDF5 dataset
mean_imag_value	Mean value of the imaginary part of a complex-valued HDF5 dataset
max_imag_value	Maximum value of the imaginary part of a complex-valued HDF5 dataset
sample_standard_deviation_imag	Sample standard deviation of the imaginary part of a complex-valued HDF5 dataset

Table 3-8. GSLC HDF5 datasets populated with statistical attributes.

HDF5 Group	HDF5 Datasets	Dataset type
/science/{L/S}SAR/GSLC/grids/frequency{A/B}	HH, HV, VH, VV, RH, RV	Complex-valued

### 3.3 Granule Definition

NISAR L2\_GSLC Granules will conform to the Tiling Scheme being developed for the mission and are expected to have a ground footprint of 240 km x 240 km.

### 3.4 File Naming Convention

NISAR L2\_GSLC Granule names will conform to the SDS L-SAR Product File Naming Conventions [RD3].

### 3.5 Temporal Organization

Temporal organization is not specifically applicable to the L2\_GSLC product, although it is generally arranged in order of increasing azimuth time.

## 3.6 Spatial Organization

The L2 data are arranged on a uniformly spaced, North-up and West-left grid – i.e., decreasing North or Y coordinate in the row direction and increasing East or X coordinate in the column direction following the row-major order convention of representing 2D raster arrays. Pixel-is-area convention (see Appendix B: Geocoded Product Grids) is used to tag the raster layers with coordinate information.

## 3.7 Spatial Sampling and Resolution

Some salient features of the output grid for the L2\_GSLC product are:

1. The top-left corner of the top-left pixel will correspond to the same geographic coordinate for all imagery layers in an L-SAR L2\_GSLC product – frequency A and frequency B.
2. The main (frequency A) and auxiliary (frequency B) bands of L-SAR data will share an exact integer scaling relationship to allow for easy inter-comparison (Table 2-3).

### 3.7.1 Mosaicking

The spatial sampling of the output grid has been designed to facilitate along-track mosaicking of contiguous L2\_GSLC product granules. See Appendix B: Geocoded Product Grids for details on common output grid used for all L2 products.

Note that L2\_GSLC products generated from L1\_RSLC products with different central frequencies cannot be mosaicked for applications that expect phase continuity.

### 3.7.2 Partially Compressed L1\_RSLC Data

Partially compressed (processed) data in L1\_RSLC files are not used to produce the L2\_GSLC products.

## 4 LEVEL 2 GEOCODED SINGLE LOOK COMPLEX PRODUCT

In this section, we briefly describe the layout of L2\_GSLC data and associated metadata in the NISAR HDF5 file. The L2\_GSLC product contains imagery layers as Digital Numbers (DNs) with secondary layer LUTs to convert to beta0, sigma0 and gamma0 with respect to the WGS84 Ellipsoid. In this section, we focus on the organization of L-SAR instrument data under the Group name “/science/LSAR”.

### 4.1 Dimensions and Shapes of Data

Information on the dimensions and shapes of the data items in various data tables is described as part of the metadata (Sec 5.1). This information is useful both as part of the product identification and for setting up further processing, i.e., dimensioning arrays.

### 4.2 Product Identification

Information needed to identify this particular product is given under the Group “/science/LSAR/identification” (Sec 5.2). This includes information such as orbit number, track-frame number, acquisition times, a polygon representing the bounding box of the included imagery in geographic coordinates, and product version.

### 4.3 Radar Imagery

The primary data elements for the granule are in the group “/science/LSAR/GSLC/grids” with subgroups for frequencyA and frequencyB (if present). Imagery layers are further organized as individual 2D datasets by polarization (TxRx) under ../frequency[A|B]. The details of the data elements are given in Section 5.3.

## 4.4 Radar Metadata

Radar metadata needed to interpret the amplitude and phase information, as well as the geolocation of the imagery are organized under the folder “/science/LSAR/GSLC/metadata”.

### 4.4.1 Calibration Information

The subgroup “calibrationInformation” contains two major types of information: radiometric calibration and radar information. The complete list of calibration information fields is given in Section 5.4.

#### 4.4.1.1 Radiometric Calibration

Secondary Lookup tables (LUT), common to all frequencies and polarizations as these are purely a function of imaging geometry, are organized under the subgroup “calibrationInformation/geometry”. The radar imagery themselves are provided as Digital Numbers (DNs). LUTs are provided to transform the DN to  $\beta_0$ ,  $\sigma_0$  and  $\gamma_0$  (with respect to the reference ellipsoid) as follows:

$$\begin{aligned}\beta_0 &= \text{abs}(\text{RSLC})^2 / \beta_0\_LUT^2 \\ \sigma_0 &= \text{abs}(\text{RSLC})^2 / \sigma_0\_LUT^2 \\ \gamma_0 &= \text{abs}(\text{RSLC})^2 / \gamma_0\_LUT^2\end{aligned}$$

These LUTs are provided as a sparse grid in map coordinates. Values at any geographical location can be obtained using simple 2D interpolation (bilinear or higher order).

#### 4.4.1.2 Radar Information

Complex two-way antenna patterns and noise-equivalent  $\sigma_0$  ( $\text{nes}_0$ ) are organized by frequency and polarization. These datasets are provided on a sparse grid in map coordinates and values of interest at any geographical location can be estimated using simple 2D interpolation (bilinear or higher order).

### 4.4.2 Processing Information

The metadata related to processing parameters, algorithms, and inputs used to produce the product are given in Section 5.5.

#### 4.4.2.1 Parameters

Processing parameters such as Doppler centroid are organized by frequency under the subgroup “processingInformation/parameters”. Common parameters such as reference terrain height and chirp weighting parameters are also included in this subgroup. All processing parameters that vary spatially are organized on low resolution geocoded grids to allow for easy lookup based on

map coordinates. This subgroup also includes flags identifying different possible corrections applied to improve the geolocation accuracy of the product. In the current version of the product, the geolocation is corrected for ionospheric range delay and dry tropospheric range delay. The ionospheric delay is estimated using GNSS-based TEC data and corrected during the geocoding process. The dry tropospheric delay is computed using a static model [RD1] and corrected during focusing the RSLC product. The subgroup also includes a flag for possible radio frequency interference (RFI) correction (“rfiCorrectionApplied”) applied to the input RSLC product.

#### 4.4.2.2 Algorithm Information

The processing algorithm information is provided in the subgroup “processingInformation/algorithms/”. It includes the software version (“softwareVersion”), which is the version of the ISCE3 software that was used to generate the product, and the list of the algorithms employed in the product processing.

#### 4.4.2.3 Inputs

The key input file – L1\_RSLC granule, orbit, DEM source description, and configuration files are tracked and listed under the subgroup “processingInformation/inputs”.

#### 4.4.3 Other Radar Metadata

Section 5.6 includes the orbit ephemeris used for generating the L2\_GSLC under a subgroup named “metadata/orbit” and the attitude under a subgroup named “metadata/attitude”.

##### 4.4.3.1 Orbit

The orbit ephemeris used for generating the L2\_GSLC product can be found under a subgroup named “orbit”. This group includes time-tagged antenna phase center position and velocity vectors in Earth Centered Earth Fixed (ECEF) cartesian coordinates. In nominal operations, this would be the MOE state vectors that were used by the L2 processor.

##### 4.4.3.2 Attitude

The attitude state vectors used for generating the L2\_GSLC product can be found under a subgroup named “attitude”. This group includes time-tagged quaternions and Euler Angles representing the slant range plane from the antenna phase center in Earth Centered Earth Fixed (ECEF) cartesian system. In nominal operations, this would be the restituted attitude state vectors that were used by the L2 processor.

#### 4.4.4 Radar Grid

Section 5.7 contains information describing the radar geometry of the sensor during data taking in the group `"/science/LSAR/GCOV/metadata/radarGrid/"`. This information is given in the form of data cubes, referred to as *radar grid cubes*, that are organized over a three-dimensional geographic grid. The representation as data cubes, rather than two-dimensional rasters, is used to reduce the amount of space required to store radar geometry values within NISAR L2 products. This is possible because each radar grid cube contains slowly-varying values in space that can be described by a low-resolution three-dimensional grid with sufficient accuracy.

These values, however, are usually required at the terrain height, often characterized by a fast-varying surface representing the local topography. A higher-resolution DEM can then be used to interpolate radar grid cubes and generate high-resolution maps of the corresponding radar geometry variable.

Radar grid cubes (for geocoded products) are provided in the same coordinate system as the product imagery with similar extents (bounding box) but coarser pixel spacing. The three-dimensional geographic grid is defined by the HDF5 datasets `"xCoordinates"` (defining the east component), `"yCoordinates"` (north component), and `"heightAboveEllipsoid"` (height above the WGS84 ellipsoid), common to all radar grid cubes, and following CF conventions 1.8.

Radar grid cubes provide the following list of radar geometry information in the associated HDF5 datasets:

1. The zero-Doppler radar grid is defined through the datasets `"slantRange"` and `"zeroDopplerAzimuthTime"`, which contain respectively the range position in meters and the zero-Doppler azimuth time in seconds for each point of the geographic grid.
2. The line-of-sight (LOS) unit vector, i.e., the vector from the target to the sensor, is defined by the datasets `"losUnitVectorX"` and `"losUnitVectorY"` which contain respectively the east and north components of the LOS unit vector in the east-north-up (ENU) coordinate system for each point of the geographic grid. Note that the third ("up") component of the LOS unit vector  $e_z$  is not provided in the product as it can be simply derived from the other two components as

$$e_z = \sqrt{1 - e_x^2 - e_y^2}$$

3. The along-track unit vector represents the projection of the along-track vector at the ground height. It is defined by the datasets `"alongTrackUnitVectorX"` and `"alongTrackUnitVectorY"` containing respectively the east and north components of the along-track unit vector in UTM coordinates.
4. The incidence angle, i.e., the angle between the LOS vector and the normal to the ellipsoid at the target height, is given by the dataset `"incidenceAngle"`.
5. The elevation angle, defined as the angle between the LOS vector and the normal to the ellipsoid at the sensor, is provided as `"elevationAngle"`.
6. The ground track velocity which contains the absolute value of the platform velocity scaled at the target height is given as `"groundTrackVelocity"`.



## 5 PRODUCT SPECIFICATION

### 5.1 Dimensions and Shapes

To simplify the description of the layout of data within the HDF5 file, we will use a table of dimensions and shapes to represent the relationship between similarly sized datasets. The entries in this table do not present actual datasets in the HDF5. This table is meant to be a guide to interpreting the shapes of the datasets in subsequent subsections.

Table 5-1 Table of dimensions and shapes in L2\_GSLC product

Name	Shape	Description
scalar	scalar	None
numberOfDatatakes	scalar	number of datatakes in product
numberOfObservations	scalar	number of observations in product
numberOfFrequencies	scalar	Number of L-SAR frequencies in product
yCoordinateLength	scalar	Number of lines in all L-SAR imagery datasets
numberOfFrequencyAPolarizations	scalar	Number of polarization layers associated with L-SAR frequency A
frequencyAWidth	scalar	Number of pixels in all L-SAR frequency A imagery datasets
complexDataFrequencyAShape	(yCoordinateLength, frequencyAWidth)	Shape associated with L-SAR frequency A imagery datasets
numberOfFrequencyBPolarizations	scalar	Number of polarization layers associated with L-SAR frequency B
frequencyBWidth	scalar	Number of pixels in all L-SAR frequency B imagery datasets
complexDataFrequencyBShape	(yCoordinateLength, frequencyBWidth)	Shape associated with L-SAR frequency B imagery datasets
validSamplesShape	(zeroDopplerTimeLength, 2)	Shape associated with L-SAR valid samples dataset
radarCubeShape	(radarCubeHeight, radarCubeLength, radarCubeWidth)	Shape associated with metadata cubes
radarGridShape	(radarCubeLength, radarCubeWidth)	Shape associated with metadata 2D layers
radarCubeHeight	scalar	Height dimension of the metadata cube
radarCubeLength	scalar	Length dimension of the metadata cube
radarCubeWidth	scalar	Width dimension of the metadata cube
dopplerCentroidLength	scalar	Length dimension of Doppler centroid grid
dopplerCentroidWidth	scalar	Length dimension of Doppler centroid grid
dopplerCentroidShape	(dopplerCentroidLength, dopplerCentroidWidth)	Shape of the Doppler centroid grid
calibrationLength	scalar	Length of calibration LUTs
calibrationWidth	scalar	Width of calibration LUTs
calibrationScaleShape	(calibrationTimeLength, calibrationSlantRangeWidth)	Shape of calibration LUTs
antennaPatternComplexShape	(calibrationTimeLength, calibrationSlantRangeWidth)	Shape of antenna pattern datasets

crosstalkComplexShape	(calibrationTimeLength, calibrationSlantRangeWidth)	Shape of crosstalk datasets
orbitListLength	scalar	description="Number of orbit state vectors
orbitShape	(orbitListLength, 3)	Shape of orbit state vector triplets dataset
attitudeListLength	scalar	Number of attitude state vectors
attitudeQuaternionShape	(attitudeListLength, 4)	Shape of attitude quaternion dataset
attitudeShape	(attitudeListLength, 3)	Shape of attitude Euler angle triplets dataset
chirpWeightingFrequencyLength	scalar	Shape associated with 1D filter representations in frequency domain
numberOfInputL1Files	scalar	Number of input L1 SLC granules
numberOfInputOrbitFiles	scalar	Number of input orbit files
numberOfInputConfigFiles	scalar	Number of input configuration files

## 5.2 Product Identification

Table 5-2 NISAR HDF5 variables used for product identification

<b>Product Identification Variables</b>		
<b>/science/LSAR/identification/absoluteOrbitNumber</b>		
<b>Type: UInt32</b>	<b>Shape: scalar</b>	
<b>Description:</b> Absolute orbit number		
units	unitless	
<b>/science/LSAR/identification/trackNumber</b>		
<b>Type: UInt16</b>	<b>Shape: scalar</b>	
<b>Description:</b> Track number		
units	unitless	
<b>/science/LSAR/identification/frameNumber</b>		
<b>Type: UInt16</b>	<b>Shape: scalar</b>	
<b>Description:</b> Frame number		
units	unitless	
<b>/science/LSAR/identification/missionId</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Mission identifier		
<b>/science/LSAR/identification/processingCenter</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Data processing center		
<b>/science/LSAR/identification/productType</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Product type		
<b>/science/LSAR/identification/granuleId</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Unique granule identification name		
<b>/science/LSAR/identification/productVersion</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Product version which represents the structure of the product and the science content governed by the algorithm, input data, and processing parameters		
<b>/science/LSAR/identification/productSpecificationVersion</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Product specification version which represents the schema of this product		
<b>/science/LSAR/identification/lookDirection</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Look direction can be left or right		
<b>/science/LSAR/identification/orbitPassDirection</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Orbit direction can be ascending or descending		
<b>/science/LSAR/identification/zeroDopplerStartTime</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Azimuth start time of the product		
<b>/science/LSAR/identification/zeroDopplerEndTime</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> Azimuth stop time of the product		
<b>/science/LSAR/identification/plannedDatatakeId</b>		
<b>Type: string</b>	<b>Shape: (numberOfDatatakes)</b>	

<b>Description:</b> List of planned datatakes included in the product	
<b>/science/LSAR/identification/plannedObservationId</b>	
<b>Type:</b> string	<b>Shape:</b> (numberOfObservations)
<b>Description:</b> List of planned observations included in the product	
<b>/science/LSAR/identification/isUrgentObservation</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> Flag indicating if observation is nominal ("False") or urgent ("True")	
<b>/science/LSAR/identification/listOfFrequencies</b>	
<b>Type:</b> string	<b>Shape:</b> (numberOfFrequencies)
<b>Description:</b> List of frequency layers available in the product	
<b>/science/LSAR/identification/diagnosticModeFlag</b>	
<b>Type:</b> UByte	<b>Shape:</b> scalar
<b>Description:</b> Indicates if the radar operation mode is a diagnostic mode (1-2) or DBFed science (0): 0, 1, or 2	
units	unitless
<b>/science/LSAR/identification/productLevel</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> Product level. L0A: Unprocessed instrument data; L0B: Reformatted, unprocessed instrument data; L1: Processed instrument data in radar coordinates system; and L2: Processed instrument data in geocoded coordinates system	
<b>/science/LSAR/identification/isGeocoded</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> Flag to indicate if the product data is in the radar geometry ("False") or in the map geometry ("True")	
<b>/science/LSAR/identification/boundingPolygon</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> OGR compatible WKT representation of bounding polygon of the image	
<b>/science/LSAR/identification/processingDateTime</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> Processing UTC date and time in the format YYYY-MM-DDTHH:MM:SS	
<b>/science/LSAR/identification/radarBand</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> Acquired frequency band	
<b>/science/LSAR/identification/instrumentName</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> Name of the instrument used to collect the remote sensing data provided in this product	
<b>/science/LSAR/identification/processingType</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> NOMINAL (or) URGENT (or) CUSTOM (or) UNDEFINED	
<b>/science/LSAR/identification/isDithered</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> "True" if the pulse timing was varied (dithered) during acquisition, "False" otherwise.	
<b>/science/LSAR/identification/isMixedMode</b>	
<b>Type:</b> string	<b>Shape:</b> scalar
<b>Description:</b> "True" if this product is a composite of data collected in multiple radar modes, "False" otherwise.	

## 5.3 Radar Imagery

Table 5-3 NISAR HDF5 variables related to SAR imagery

<b>Product Imagery Variables</b>		
<b>/science/LSAR/GSLC/grids/frequencyA/yCoordinates</b>		
<b>Type: Float64</b>	<b>Shape: (yCoordinateLength)</b>	
<b>Description:</b> CF compliant dimension associated with the Y coordinates		
units	meters	
<b>/science/LSAR/GSLC/grids/frequencyB/yCoordinates</b>		
<b>Type: Float64</b>	<b>Shape: (yCoordinateLength)</b>	
<b>Description:</b> CF compliant dimension associated with the Y coordinates		
units	meters	
<b>/science/LSAR/GSLC/grids/frequencyA/listOfPolarizations</b>		
<b>Type: string</b>	<b>Shape: (numberOfFrequencyAPolarizations)</b>	
<b>Description:</b> List of processed polarization layers with frequencyA		
<b>/science/LSAR/GSLC/grids/frequencyA/yCoordinateSpacing</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Nominal spacing in meters between consecutive lines		
units	meters	
<b>/science/LSAR/GSLC/grids/frequencyA/xCoordinateSpacing</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Nominal spacing in meters between consecutive pixels		
units	meters	
<b>/science/LSAR/GSLC/grids/frequencyA/rangeBandwidth</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Processed range bandwidth in Hz		
units	Hz	
<b>/science/LSAR/GSLC/grids/frequencyA/azimuthBandwidth</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Processed azimuth bandwidth in Hz		
units	Hz	
<b>/science/LSAR/GSLC/grids/frequencyA/centerFrequency</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Center frequency of the processed image in Hz		
units	Hz	
<b>/science/LSAR/GSLC/grids/frequencyA/slantRangeSpacing</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Slant range spacing of grid. Same as difference between consecutive samples in slantRange array		
units	meters	
<b>/science/LSAR/GSLC/grids/frequencyA/zeroDopplerTimeSpacing</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Time interval in the along track direction for raster layers. This is same as the spacing between consecutive entries in the zeroDopplerTime array		
units	seconds	
<b>/science/LSAR/GSLC/grids/frequencyA/projection</b>		
<b>Type: Int32</b>	<b>Shape: scalar</b>	
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	

	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/grids/frequencyA/projection</b>		
<b>Type: Int32</b>		<b>Shape: scalar</b>
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/grids/frequencyA/xCoordinates</b>		
<b>Type: Float64</b>		<b>Shape: (frequencyAWidth)</b>
<b>Description:</b> CF compliant dimension associated with the X coordinates		
	units	meters
<b>/science/LSAR/GSLC/grids/frequencyA/yCoordinates</b>		
<b>Type: Float64</b>		<b>Shape: (frequencyAWidth)</b>
<b>Description:</b> CF compliant dimension associated with the Y coordinates		
	units	meters
<b>/science/LSAR/GSLC/grids/frequencyA/mask</b>		
<b>Type: Byte</b>		<b>Shape: (yCoordinateLength, frequencyAWidth)</b>
<b>Description:</b> GSLC mask		
	units	unitless
<b>/science/LSAR/GSLC/grids/frequencyA/HH</b>		
<b>Type: CFloat32</b>		<b>Shape: (yCoordinateLength, frequencyAWidth)</b>
<b>Description:</b> Focused SLC image (HH)		
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyA/HV</b>		
<b>Type: CFloat32</b>		<b>Shape: (yCoordinateLength, frequencyAWidth)</b>
<b>Description:</b> Focused SLC image (HV)		
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyA/VH</b>		
<b>Type: CFloat32</b>		<b>Shape: (yCoordinateLength, frequencyAWidth)</b>

<b>Description:</b> Focused SLC image (VH)		
units		DN
<b>/science/LSAR/GSLC/grids/frequencyA/VV</b>		
<b>Type:</b> CFloat32		<b>Shape:</b> (yCoordinateLength, frequencyAWidth)
<b>Description:</b> Focused SLC image (VV)		
units		DN
<b>/science/LSAR/GSLC/grids/frequencyA/RH</b>		
<b>Type:</b> CFloat32		<b>Shape:</b> (yCoordinateLength, frequencyAWidth)
<b>Description:</b> Focused SLC image (RH)		
units		DN
<b>/science/LSAR/GSLC/grids/frequencyA/RV</b>		
<b>Type:</b> CFloat32		<b>Shape:</b> (yCoordinateLength, frequencyAWidth)
<b>Description:</b> Focused SLC image (RV)		
units		DN
<b>/science/LSAR/GSLC/grids/frequencyA/numberOfSubSwaths</b>		
<b>Type:</b> UByte		<b>Shape:</b> scalar
<b>Description:</b> Number of swaths of continuous imagery, due to transmit gaps		
units		unitless
<b>/science/LSAR/GSLC/grids/frequencyB/listOfPolarizations</b>		
<b>Type:</b> string		<b>Shape:</b> (numberOfFrequencyBPolarizations)
<b>Description:</b> List of processed polarization layers with frequencyA		
<b>/science/LSAR/GSLC/grids/frequencyB/yCoordinateSpacing</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Nominal spacing in meters between consecutive lines		
units		meters
<b>/science/LSAR/GSLC/grids/frequencyB/xCoordinateSpacing</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Nominal spacing in meters between consecutive pixels		
units		meters
<b>/science/LSAR/GSLC/grids/frequencyB/rangeBandwidth</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Processed range bandwidth in Hz		
units		Hz
<b>/science/LSAR/GSLC/grids/frequencyB/azimuthBandwidth</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Processed azimuth bandwidth in Hz		
units		Hz
<b>/science/LSAR/GSLC/grids/frequencyB/centerFrequency</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Center frequency of the processed image in Hz		
units		Hz
<b>/science/LSAR/GSLC/grids/frequencyB/slantRangeSpacing</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Slant range spacing of grid. Same as difference between consecutive samples in slantRange array		
units		meters
<b>/science/LSAR/GSLC/grids/frequencyB/zeroDopplerTimeSpacing</b>		
<b>Type:</b> Float64		<b>Shape:</b> scalar
<b>Description:</b> Time interval in the along track direction for raster layers. This is same as the spacing between consecutive entries in the zeroDopplerTime array		
units		seconds
<b>/science/LSAR/GSLC/grids/frequencyB/projection</b>		
<b>Type:</b> Int32		<b>Shape:</b> scalar
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		

	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/grids/frequencyB/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (frequencyBWidth)</b>
	<b>Description:</b> CF compliant dimension associated with the X coordinates	
	units	meters
<b>/science/LSAR/GSLC/grids/frequencyB/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (frequencyBWidth)</b>
	<b>Description:</b> CF compliant dimension associated with the Y coordinates	
	units	meters
<b>/science/LSAR/GSLC/grids/frequencyB/mask</b>		
	<b>Type: Byte</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> GSLC mask	
	units	unitless
<b>/science/LSAR/GSLC/grids/frequencyB/HH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> Focused SLC image (HH)	
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyB/HV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> Focused SLC image (HV)	
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyB/VH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> Focused SLC image (VH)	
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyB/VV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> Focused SLC image (VV)	
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyB/RH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> Focused SLC image (RH)	
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyB/RV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (yCoordinateLength, frequencyBWidth)</b>
	<b>Description:</b> Focused SLC image (RV)	
	units	DN
<b>/science/LSAR/GSLC/grids/frequencyB/numberOfSubSwaths</b>		
	<b>Type: UByte</b>	<b>Shape: scalar</b>



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<b>Description:</b> Number of swaths of continuous imagery, due to transmit gaps		
	units	unitless

## 5.4 Calibration Information

Table 5-4 NISAR HDF5 variables related to calibration

<b>Calibration-related variables</b>		
<b>/science/LSAR/GSLC/metadata/calibrationInformation/geometry/projection</b>		
<b>Type: Int32</b>	<b>Shape: scalar</b>	
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	
false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.	
false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.	
grid_mapping_name	Grid mapping variable name	
inverse_flattening	Inverse flattening of the ellipsoidal figure	
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.	
longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.	
semi_major_axis	Semi-major axis	
spatial_ref	Spatial reference	
utm_zone_number	UTM zone number	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/geometry/yCoordinates</b>		
<b>Type: Float64</b>	<b>Shape: (calibrationLength)</b>	
<b>Description:</b> Y coordinate dimension corresponding to calibration records		
units	meters	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/geometry/xCoordinates</b>		
<b>Type: Float64</b>	<b>Shape: (calibrationWidth)</b>	
<b>Description:</b> X coordinate dimension corresponding to calibration records		
units	meters	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/geometry/beta0</b>		
<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>	
<b>Description:</b> 2D LUT to convert DN to beta 0 assuming as a function of geographical location		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/geometry/sigma0</b>		
<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>	
<b>Description:</b> 2D LUT to convert DN to sigma 0 assuming as a function of geographical location		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/geometry/gamma0</b>		
<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>	
<b>Description:</b> 2D LUT to convert DN to gamma 0 as a function of geographical location		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/projection</b>		
<b>Type: Int32</b>	<b>Shape: scalar</b>	
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	
false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.	

	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationLength)</b>
<b>Description:</b> Y coordinates dimension corresponding to calibration records		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationWidth)</b>
<b>Description:</b> X coordinates dimension corresponding to calibration records		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/HH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/HV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/VH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/VV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/RH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/elevationAntennaPattern/RV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/projection</b>		
	<b>Type: Int32</b>	<b>Shape: scalar</b>
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name

	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationLength)</b>
<b>Description:</b> Y coordinates dimension corresponding to calibration records		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationWidth)</b>
<b>Description:</b> X coordinates dimension corresponding to calibration records		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/HH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/HV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/VH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/VV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/RH</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/elevationAntennaPattern/RV</b>		
	<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Complex two-way elevation antenna pattern		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/projection</b>		
	<b>Type: Int32</b>	<b>Shape: scalar</b>
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.

	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationLength)</b>
	<b>Description:</b> Y coordinates dimension corresponding to calibration records	
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationWidth)</b>
	<b>Description:</b> X coordinates dimension corresponding to calibration records	
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/HH</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
	<b>Description:</b> Noise equivalent sigma zero	
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/HV</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
	<b>Description:</b> Noise equivalent sigma zero	
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/VH</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
	<b>Description:</b> Noise equivalent sigma zero	
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/VV</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
	<b>Description:</b> Noise equivalent sigma zero	
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/RH</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
	<b>Description:</b> Noise equivalent sigma zero	
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/nes0/RV</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
	<b>Description:</b> Noise equivalent sigma zero	
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/projection</b>		
	<b>Type: Int32</b>	<b>Shape: scalar</b>
	<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes	
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis

	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationLength)</b>
<b>Description:</b> Y coordinates dimension corresponding to calibration records		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (calibrationWidth)</b>
<b>Description:</b> X coordinates dimension corresponding to calibration records		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/HH</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Noise equivalent sigma zero		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/HV</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Noise equivalent sigma zero		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/VH</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Noise equivalent sigma zero		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/VV</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Noise equivalent sigma zero		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/RH</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Noise equivalent sigma zero		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/nes0/RV</b>		
	<b>Type: Float32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Noise equivalent sigma zero		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/projection</b>		
	<b>Type: Int32</b>	<b>Shape: scalar</b>
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/yCoordinates</b>		

<b>Type: Float64</b>	<b>Shape: (calibrationLength)</b>
<b>Description:</b> Y coordinates dimension corresponding to crosstalk records	
units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/xCoordinates</b>	
<b>Type: Float64</b>	<b>Shape: (calibrationWidth)</b>
<b>Description:</b> X coordinates dimension corresponding to crosstalk records	
units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/txHorizontalCrosspol</b>	
<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Crosstalk in H-transmit channel expressed as ratio txV / txH	
units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/txVerticalCrosspol</b>	
<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Crosstalk in V-transmit channel expressed as ratio txH / txV	
units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/rxHorizontalCrosspol</b>	
<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Crosstalk in H-recv channel expressed as ratio rxV / rxH	
units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/crosstalk/rxVerticalCrosspol</b>	
<b>Type: CFloat32</b>	<b>Shape: (calibrationTimeLength, calibrationSlantRangeWidth)</b>
<b>Description:</b> Crosstalk in V-recv channel expressed as ratio rxH / rxV	
units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/commonDelay</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to all polarimetric channels	
units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/faradayRotation</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Faraday rotation correction applied in processing	
units	radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HH/differentialDelay</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to HH channel	
units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HH/differentialPhase</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Phase correction applied to HH channel	
units	radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HH/scaleFactor</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Scale factor applied to HH channel complex amplitude (at antenna boresite)	
units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HH/scaleFactorSlope</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Slope of scale factor applied to HH channel complex amplitude with respect to elevation angle	
units	radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HV/differentialDelay</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to HV channel	
units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HV/differentialPhase</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>



<b>Description:</b> Phase correction applied to HV channel		
units		radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HV/scaleFactor</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Scale factor applied to HV channel complex amplitude (at antenna boresite)		
units		unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/HV/scaleFactorSlope</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Slope of scale factor applied to HV channel complex amplitude with respect to elevation angle		
units		radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VH/differentialDelay</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to VH channel		
units		meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VH/differentialPhase</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Phase correction applied to VH channel		
units		radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VH/scaleFactor</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Scale factor applied to VH channel complex amplitude (at antenna boresite)		
units		unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VH/scaleFactorSlope</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Slope of scale factor applied to VH channel complex amplitude with respect to elevation angle		
units		radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VV/differentialDelay</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to VV channel		
units		meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VV/differentialPhase</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Phase correction applied to VV channel		
units		radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VV/scaleFactor</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Scale factor applied to VV channel complex amplitude (at antenna boresite)		
units		unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/VV/scaleFactorSlope</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Slope of scale factor applied to VV channel complex amplitude with respect to elevation angle		
units		radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RH/differentialDelay</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to RH channel		
units		meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RH/differentialPhase</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Phase correction applied to RH channel		
units		radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RH/scaleFactor</b>		
<b>Type: Float64</b>		<b>Shape: scalar</b>
<b>Description:</b> Scale factor applied to RH channel complex amplitude (at antenna boresite)		



	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RH/scaleFactorSlope</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Slope of scale factor applied to RH channel complex amplitude with respect to elevation angle		
	units	radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RV/differentialDelay</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Range delay correction applied to RV channel		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RV/differentialPhase</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Phase correction applied to RV channel		
	units	radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RV/scaleFactor</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Scale factor applied to RV channel complex amplitude (at antenna boresite)		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyA/RV/scaleFactorSlope</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Slope of scale factor applied to RV channel complex amplitude with respect to elevation angle		
	units	radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/commonDelay</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Range delay correction applied to all polarimetric channels		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/faradayRotation</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Faraday rotation correction applied in processing		
	units	radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HH/differentialDelay</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Range delay correction applied to HH channel		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HH/differentialPhase</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Phase correction applied to HH channel		
	units	radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HH/scaleFactor</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Scale factor applied to HH channel complex amplitude (at antenna boresite)		
	units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HH/scaleFactorSlope</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Slope of scale factor applied to HH channel complex amplitude with respect to elevation angle		
	units	radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HV/differentialDelay</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Range delay correction applied to HV channel		
	units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HV/differentialPhase</b>		
<b>Type:</b>	Float64	<b>Shape:</b> scalar
<b>Description:</b> Phase correction applied to HV channel		
	units	radians

<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HV/scaleFactor</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Scale factor applied to HV channel complex amplitude (at antenna boresite)		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/HV/scaleFactorSlope</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Slope of scale factor applied to HV channel complex amplitude with respect to elevation angle		
units	radians <sup>-1</sup>	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VH/differentialDelay</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Range delay correction applied to VH channel		
units	meters	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VH/differentialPhase</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Phase correction applied to VH channel		
units	radians	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VH/scaleFactor</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Scale factor applied to VH channel complex amplitude (at antenna boresite)		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VH/scaleFactorSlope</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Slope of scale factor applied to VH channel complex amplitude with respect to elevation angle		
units	radians <sup>-1</sup>	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VV/differentialDelay</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Range delay correction applied to VV channel		
units	meters	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VV/differentialPhase</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Phase correction applied to VV channel		
units	radians	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VV/scaleFactor</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Scale factor applied to VV channel complex amplitude (at antenna boresite)		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/VV/scaleFactorSlope</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Slope of scale factor applied to VV channel complex amplitude with respect to elevation angle		
units	radians <sup>-1</sup>	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RH/differentialDelay</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Range delay correction applied to RH channel		
units	meters	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RH/differentialPhase</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Phase correction applied to RH channel		
units	radians	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RH/scaleFactor</b>		
<b>Type: Float64</b>	<b>Shape: scalar</b>	
<b>Description:</b> Scale factor applied to RH channel complex amplitude (at antenna boresite)		
units	unitless	
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RH/scaleFactorSlope</b>		

<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Slope of scale factor applied to RH channel complex amplitude with respect to elevation angle	
units	radians <sup>-1</sup>
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RV/differentialDelay</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Range delay correction applied to RV channel	
units	meters
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RV/differentialPhase</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Phase correction applied to RV channel	
units	radians
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RV/scaleFactor</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Scale factor applied to RV channel complex amplitude (at antenna boresite)	
units	unitless
<b>/science/LSAR/GSLC/metadata/calibrationInformation/frequencyB/RV/scaleFactorSlope</b>	
<b>Type: Float64</b>	<b>Shape: scalar</b>
<b>Description:</b> Slope of scale factor applied to RV channel complex amplitude with respect to elevation angle	
units	radians <sup>-1</sup>

## 5.5 Processing Information

Table 5-5 NISAR HDF5 variables related to processing parameters

<b>Processing-related variables</b>		
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/azimuthChirpWeighting</b>		
<b>Type:</b> Float32	<b>Shape:</b> (chirpFFTFrequency)	
<b>Description:</b> 1-D array in frequency domain for azimuth processing. This is used for processing L0b to L1. FFT length=256 (assumed)		
	spacing	
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/rangeChirpWeighting</b>		
<b>Type:</b> Float32	<b>Shape:</b> (chirpFFTFrequency)	
<b>Description:</b> 1-D array in frequency domain for range processing. This is used for processing L0b to L1. FFT length=256 (assumed)		
	spacing	
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/dryTroposphericGeolocationCorrectionApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the dry tropospheric correction has been applied to improve geolocation		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/wetTroposphericGeolocationCorrectionApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the wet tropospheric correction has been applied to improve geolocation		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/rangeIonosphericGeolocationCorrectionApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the range ionospheric correction has been applied to improve geolocation		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/azimuthIonosphericGeolocationCorrectionApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the azimuth ionospheric correction has been applied to improve geolocation		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/rfiCorrectionApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the input RSLC was corrected for RFI		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/ellipsoidalFlatteningApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the GSLC phase has been flattened with respect to a zero height ellipsoid		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/topographicFlatteningApplied</b>		
<b>Type:</b> string	<b>Shape:</b> scalar	
<b>Description:</b> Flag to indicate if the GSLC phase has been flattened with respect to topographic height using a DEM		
	units	unitless
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/referenceTerrainHeight</b>		
<b>Type:</b> Float32	<b>Shape:</b> (dopplerCentroidLength, dopplerCentroidWidth)	
<b>Description:</b> Reference Terrain Height as a function of geographical location		
	units	meters
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/projection</b>		
<b>Type:</b> Int32	<b>Shape:</b> scalar	
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
	ellipsoid	Projection ellipsoid

	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (dopplerCentroidTimeLength)</b>
	<b>Description: Y coordinate dimension corresponding to processing information records</b>	
	units	meters
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (dopplerCentroidSlantRangeWidth)</b>
	<b>Description: X coordinate dimension corresponding to processing information records"</b>	
	units	meters
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyA/projection</b>		
	<b>Type: Int32</b>	<b>Shape: scalar</b>
	<b>Description: Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes</b>	
	ellipsoid	Projection ellipsoid
	epsg_code	Projection EPSG code
	false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.
	false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.
	grid_mapping_name	Grid mapping variable name
	inverse_flattening	Inverse flattening of the ellipsoidal figure
	latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.
	longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.
	semi_major_axis	Semi-major axis
	spatial_ref	Spatial reference
	utm_zone_number	UTM zone number
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyA/yCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (dopplerCentroidTimeLength)</b>
	<b>Description: Y coordinate dimension corresponding to processing information records</b>	
	units	meters
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyA/xCoordinates</b>		
	<b>Type: Float64</b>	<b>Shape: (dopplerCentroidSlantRangeWidth)</b>
	<b>Description: X coordinate dimension corresponding to processing information records"</b>	
	units	meters
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyA/dopplerCentroid</b>		
	<b>Type: Float64</b>	<b>Shape: (dopplerCentroidLength, dopplerCentroidWidth)</b>
	<b>Description: 2D LUT of Doppler Centroid for Frequency A</b>	
	units	Hz
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyB/projection</b>		

<b>Type: Int32</b>		<b>Shape: scalar</b>
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	
false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.	
false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.	
grid_mapping_name	Grid mapping variable name	
inverse_flattening	Inverse flattening of the ellipsoidal figure	
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.	
longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.	
semi_major_axis	Semi-major axis	
spatial_ref	Spatial reference	
utm_zone_number	UTM zone number	
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyB/yCoordinates</b>		
<b>Type: Float64</b>		<b>Shape: (dopplerCentroidTimeLength)</b>
<b>Description:</b> Y coordinate dimension corresponding to processing information records		
units	meters	
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyB/xCoordinates</b>		
<b>Type: Float64</b>		<b>Shape: (dopplerCentroidSlantRangeWidth)</b>
<b>Description:</b> X coordinate dimension corresponding to processing information records"		
units	meters	
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/frequencyB/dopplerCentroid</b>		
<b>Type: Float64</b>		<b>Shape: (dopplerCentroidLength, dopplerCentroidWidth)</b>
<b>Description:</b> 2D LUT of Doppler Centroid for Frequency B		
units	Hz	
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/runConfigurationContents</b>		
<b>Type: string</b>		<b>Shape: scalar</b>
<b>Description:</b> Contents of the run configuration file with parameters used for processing		
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/softwareVersion</b>		
<b>Type: string</b>		<b>Shape: scalar</b>
<b>Description:</b> Software version used for processing		
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/demInterpolation</b>		
<b>Type: string</b>		<b>Shape: scalar</b>
<b>Description:</b> DEM interpolation method		
<b>/science/LSAR/GSLC/metadata/processingInformation/parameters/geocoding</b>		
<b>Type: string</b>		<b>Shape: scalar</b>
<b>Description:</b> Geocoding algorithm		
<b>/science/LSAR/GSLC/metadata/processingInformation/inputs/l1SlcGranules</b>		
<b>Type: string</b>		<b>Shape: (numberOfInputLOBFiles)</b>
<b>Description:</b> List of input L1 products used		
<b>/science/LSAR/GSLC/metadata/processingInformation/inputs/orbitFiles</b>		
<b>Type: string</b>		<b>Shape: (numberOfInputOrbitFiles)</b>
<b>Description:</b> List of input orbit files used		
<b>/science/LSAR/GSLC/metadata/processingInformation/inputs/configFiles</b>		
<b>Type: string</b>		<b>Shape: (numberOfInputConfigFiles)</b>
<b>Description:</b> List of input config files used		
<b>/science/LSAR/GSLC/metadata/processingInformation/inputs/demSource</b>		
<b>Type: string</b>		<b>Shape: scalar</b>
<b>Description:</b> Description of the input digital elevation model (DEM)		

## 5.6 Other Radar Metadata

Table 5-6 NISAR HDF5 variables related to useful radar metadata

<b>Radar metadata-related variables</b>		
<b>/science/LSAR/GSLC/metadata/orbit/time</b>		
<b>Type: Float64</b>	<b>Shape: (orbitListLength)</b>	
<b>Description:</b> Time vector record. This record contains the time corresponding to position, velocity, acceleration records		
units	seconds since YYYY-MM-DD HH:MM:SS	
<b>/science/LSAR/GSLC/metadata/orbit/position</b>		
<b>Type: Float64</b>	<b>Shape: (orbitListLength, tripletxyz)</b>	
<b>Description:</b> Position vector record. This record contains the platform position data with respect to WGS84 G1762 reference frame		
units	meters	
<b>/science/LSAR/GSLC/metadata/orbit/velocity</b>		
<b>Type: Float64</b>	<b>Shape: (orbitListLength, tripletxyz)</b>	
<b>Description:</b> Velocity vector record. This record contains the platform velocity data with respect to WGS84 G1762 reference frame		
units	meters per second	
<b>/science/LSAR/GSLC/metadata/orbit/acceleration</b>		
<b>Type: Float64</b>	<b>Shape: (orbitListLength, tripletxyz)</b>	
<b>Description:</b> Acceleration vector record. This record contains the platform acceleration data with respect to WGS84 G1762 reference frame		
units	meters per second squared	
<b>/science/LSAR/GSLC/metadata/orbit/orbitType</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> PrOE (or) NOE (or) MOE (or) POE (or) Custom		
<b>/science/LSAR/GSLC/metadata/attitude/time</b>		
<b>Type: Float64</b>	<b>Shape: (orbitListLength)</b>	
<b>Description:</b> Time vector record. This record contains the time corresponding to attitude and quaternion records		
units	seconds since YYYY-MM-DD HH:MM:SS	
<b>/science/LSAR/GSLC/metadata/attitude/quaternions</b>		
<b>Type: Float64</b>	<b>Shape: (attitudeListLength, quaternions)</b>	
<b>Description:</b> Attitude quaternions (q0, q1, q2, q3)		
units	unitless	
<b>/science/LSAR/GSLC/metadata/attitude/angularVelocity</b>		
<b>Type: Float64</b>	<b>Shape: (attitudeListLength, tripletxyz)</b>	
<b>Description:</b> Attitude angular velocity vectors (wx, wy, wz)		
units	radians per second	
<b>/science/LSAR/GSLC/metadata/attitude/eulerAngles</b>		
<b>Type: Float64</b>	<b>Shape: (attitudeListLength, tripletxyz)</b>	
<b>Description:</b> Attitude Euler angles (roll, pitch, yaw)		
units	degrees	
<b>/science/LSAR/GSLC/metadata/attitude/attitudeType</b>		
<b>Type: string</b>	<b>Shape: scalar</b>	
<b>Description:</b> PrOE (or) NOE (or) MOE (or) POE (or) Custom		



## 5.7 Radar Grid

Table 5-7 NISAR HDF5 variables related to metadata cube

<b>Metadata cube-related variables</b>		
<b>/science/LSAR/GSLC/metadata/radarGrid/zeroDopplerAzimuthTime</b>		
<b>Type: Float64</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> Zero Doppler Imaging Time to target		
units	seconds since YYYY-mm-dd HH:MM:SS	
<b>/science/LSAR/GSLC/metadata/radarGrid/slantRange</b>		
<b>Type: Float64</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> Slant Range in meters to target		
units	meters	
<b>/science/LSAR/GSLC/metadata/radarGrid/incidenceAngle</b>		
<b>Type: Float32</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> Incidence angle is defined as the angle between the LOS vector and the normal to the ellipsoid at the target height		
max	90.0	
min	0.0	
units	degrees	
<b>/science/LSAR/GSLC/metadata/radarGrid/losUnitVectorX</b>		
<b>Type: Float32</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> East component of unit vector of LOS from target to sensor		
max	-1.0	
min	1.0	
units	unitless	
<b>/science/LSAR/GSLC/metadata/radarGrid/losUnitVectorY</b>		
<b>Type: Float32</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> North component of unit vector of LOS from target to sensor		
max	-1.0	
min	1.0	
units	unitless	
<b>/science/LSAR/GSLC/metadata/radarGrid/alongTrackUnitVectorX</b>		
<b>Type: Float32</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> East component of unit vector along ground track		
max	-1.0	
min	1.0	
units	unitless	
<b>/science/LSAR/GSLC/metadata/radarGrid/alongTrackUnitVectorY</b>		
<b>Type: Float32</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> North component of unit vector along ground track		
max	-1.0	
min	1.0	
units	unitless	
<b>/science/LSAR/GSLC/metadata/radarGrid/elevationAngle</b>		
<b>Type: Float32</b>	<b>Shape: (radarCubeHeight, radarCubeLength, radarCubeWidth)</b>	
<b>Description:</b> Elevation angle is defined as the angle between the LOS vector and the normal to the ellipsoid at the sensor		
max	90.0	
min	0.0	
units	degrees	
<b>/science/LSAR/GSLC/metadata/radarGrid/projection</b>		



<b>Type: Int32</b>		<b>Shape: scalar</b>
<b>Description:</b> Product map grid projection: EPSG code, with additional projection information as HDF5 Attributes		
ellipsoid	Projection ellipsoid	
epsg_code	Projection EPSG code	
false_easting	The value added to all abscissa values in the rectangular coordinates for a map projection.	
false_northing	The value added to all ordinate values in the rectangular coordinates for a map projection.	
grid_mapping_name	Grid mapping variable name	
inverse_flattening	Inverse flattening of the ellipsoidal figure	
latitude_of_projection_origin	The latitude chosen as the origin of rectangular coordinates for a map projection.	
longitude_of_projection_origin	The longitude, with respect to Greenwich, of the prime meridian associated with the geodetic datum.	
semi_major_axis	Semi-major axis	
spatial_ref	Spatial reference	
utm_zone_number	UTM zone number	
<b>/science/LSAR/GSLC/metadata/radarGrid/xCoordinates</b>		
<b>Type: Float64</b>		<b>Shape: (radarCubeWidth)</b>
<b>Description:</b> x Coordinates corresponding to the radar grid		
units	meters	
<b>/science/LSAR/GSLC/metadata/radarGrid/yCoordinates</b>		
<b>Type: Float64</b>		<b>Shape: (radarCubeWidth)</b>
<b>Description:</b> y Coordinates corresponding to the radar grid		
units	meters	
<b>/science/LSAR/GSLC/metadata/radarGrid/groundTrackVelocity</b>		
<b>Type: Float64</b>		<b>Shape: (radarCubeLength, radarCubeWidth)</b>
<b>Description:</b> Absolute value of the platform velocity scaled at the target height		
units	meters per second	
<b>/science/LSAR/GSLC/metadata/radarGrid/heightAboveEllipsoid</b>		
<b>Type: Float64</b>		<b>Shape: (radarCubeHeight)</b>
<b>Description:</b> Height values above WGS84 Ellipsoid corresponding to the location grid		
units	meters	

## 6 METADATA CUBE

In this section, we provide an overview of the metadata cubes used to store spatially-varying ancillary data in the secondary layers of the NISAR L-SAR product HDF5 granules. Note that this sparse representation is to assist users in ingesting and analyzing NISAR products within existing GIS software and is not meant to replace traditional representations of SAR data within the product granules or traditional processing approaches with radar geometry-aware software.

Metadata cubes are represented as three-dimensional arrays in the NISAR product HDF5 modules (Figure 6-1). The axes of the array are interpreted as (height, increasing azimuth time, and increasing slant range) in case of radar geometry products and as (height, decreasing northing, and increasing easting) in case of geocoded products. The data is organized with height as the first axis, as this allows one to directly ingest data as GCPs or rasters into existing GIS software. Each height layer is the same size. Metadata cubes will have fixed grid spacing (3 km in azimuth/northing x 1 km in slant range/easting x 1.5 km in height) and will allow for easy merging when multiple products along the same imaging track are to be concatenated. The metadata fields on this coarse resolution grid will be evaluated using traditional radar processing approaches without approximations. The metadata cube will also span a field slightly larger than the original image product to allow users to interpolate data without introducing edge effects.

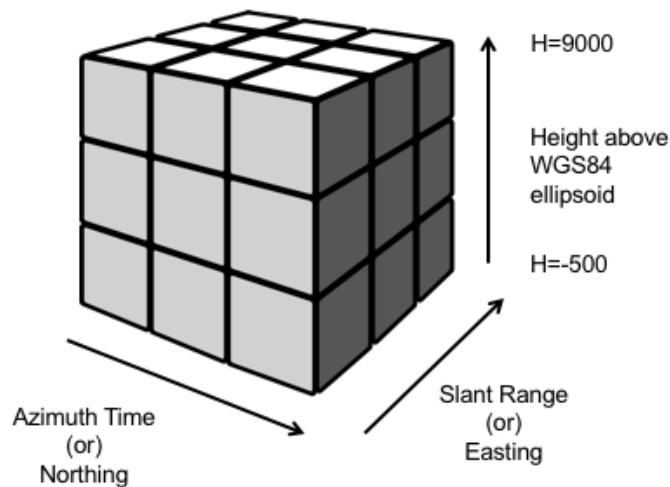


Figure 6-1. Metadata cube layer schematic

### 6.1 Metadata Cube Interpolation Example

We provide here a conceptual example of how these metadata cubes can be used. Let us consider a GSLC product on a UTM Zone 10 grid (Table 6-1). We use a geocoded product for the demonstration but the presented approach can be easily extended to radar coordinate products by replacing northing axis by azimuth time and easting axis by slant range.

Table 6-1. Example metadata cube properties

Name	Value	Description
Primary layer properties		
xmin	100000.0	Easting of the first column (m)
xmax	340000.0	Easting of the last column (m)
dx	30.0	Column spacing in Easting (m)
Nx	8001	Number of columns
ymax	570000.0	Northing of first row (m)
ymin	330000.0	Northing of last row (m)
dy	-30.0	Row spacing in Northing (m). Negative to emphasize North-up imagery in geocoded products
Ny	8001	Number of rows
Metadata cube properties		
Cxmin	97000.0	Easting of first column (m)
Cxmax	343000.0	Easting of last column (m)
Cdx	1000.0	Column spacing in Easting (m)
CNx	247	Number of columns
Cymax	579000.0	Northing of first row (m)
Cymin	321000.0	Northing of last row(m)
Cdy	-3000.0	Row spacing in Northing (m). Negative to emphasize North-up imagery in geocoded products
CNy	87	Number of rows
Czmin	-1500	Height of the first layer (m)
Czmax	9000	Height of the last layer (m)
Cdz	1500	Layer spacing in height (m)
CNz	8	Number of height layers

Suppose we are interested in computing the Perpendicular Baseline ( $B_{\text{perp}}$ ) at a pixel of interest located at UTM coordinates point  $(P_x, P_y)$ . Since these are coordinates on a map domain, we can look up a DEM to get the height at this point. The three-dimensional point of interest then becomes  $(P_x, P_y, h(P_x, P_y))$ .

The metadata cube for Perpendicular baseline can be thought of as a three-dimensional field  $B_{\text{perp}}(x, y, z)$  – even though it is oriented as  $(N_z, N_y, N_x)$  in the HDF5 file for ease of use with a GIS. The user can use standard built-in regular grid three-dimensional interpolation routines in languages like MATLAB (e.g, `interp3`), IDL or Python (e.g, `RegularGridInterpolator`) to interpolate the  $B_{\text{perp}}$  array. We recommend cubic interpolation for best results. If a three-dimensional interpolator is not available, one could use two-dimensional cubic interpolation for each height layer followed by a one-dimensional cubic interpolation in the following manner:

1. Populate  $f(i)$ ,  $i=0, \dots, N_z-1$  by two-dimensional cubic interpolation of each height layer:

$$f(i) = Bperp \left[ i, \frac{Py - Cymax}{Cdy}, \frac{Px - Cxmin}{Cdx} \right]$$

where the numbers in the square brackets indicate indices into the three-dimensional cube. For example, if we are interested in the point (107590.0 East, 555870.0 North, 300.0 Height), we would interpolate at Row 7.71 and Column 10.59 for each height layer.

2. Interpolate  $f(i)$  using one-dimensional cubic interpolation:

$$Bperp(Px, Py, h(Px, Py)) = f \left[ \frac{h(Px, Py) - Czmin}{Cdz} \right]$$

where the number in the square bracket indicates an index into a one-dimensional array. For example, for a height value of 200.0, we would interpolate at an index of 1.2.

## 6.2 Metadata Cube Usage Note

Note that the metadata cubes are designed to accommodate one double-precision cube within 1 MB of memory, allowing for information to be easily stored in memory for on-the-fly computation within GIS frameworks or software without much overhead. The metadata cubes are not a replacement for traditional SAR processing approaches or very high-resolution analyses. They are meant to facilitate rapid processing and analysis by non-experts and will serve the needs for most SAR applications. Analyses show that the geolocation error is on the order of 1.5 cm due to interpolation which is significantly smaller than errors from sources such as DEM, orbits, and atmospheric path delay. Interpolation errors for each of the metadata layers will be reported after additional study.

## APPENDIX A: ACRONYMS

ADT	Algorithm Development Team
ANF	Area Normalization Factor
AT	Along Track
ATBD	Algorithm Theoretical Basis Document
AWS	Amazon Web Services
BFPQ	Block (adaptive) Floating-Point Quantization (adaptive may indicate implementation options)
Cal/Val	Calibration and Validation (also sometimes cal/val)
CDR	Critical Design Review
CF	Climate and Forecast
CPU	Central Processing Unit
CRSD	Calibration Raw Signal Data
CSV	Comma-separated values
DAAC	Distributed Active Archive Center
DBF	Digital Beam Forming
DEM	Digital Elevation Model
DM	Diagnostic Mode
DN	Digital Number
EAR	Export Administration Regulations
EASE	Equal-Area Scalable Earth
ECMWF	European Centre for Medium-Range Weather Forecasts
ECEF	Earth Centered Earth Fixed
ER#.#	Engineering Release #.#
ERA5	ECMWF Reanalysis 5th generation
FFT	Fast Fourier Transform
FM	Frequency Modulation
FOE	Forecast Orbit Ephemeris
FOV	Field of View
GCOV	Geocoded Polarimetric Covariance (L2_GCOV)
GCP	Ground Control Point
GDAL	Geospatial Data Abstraction Library
GDS	Ground Data System
GeoTIFF	Geographic Tagged Image File Format
GIS	Geographic Information System
GMTED	Global Multi-resolution Terrain Elevation Data
GNSS	Global Navigation Satellite System
GOFF	Geocoded Pixel Offsets (L2_GOFF)
GPU	Graphics Processing Unit
GSLC	Geocoded Single Look Complex (L2_GSLC)
GUNW	Geocoded Unwrapped Interferogram (L2_GUNW)
HH	Horizontal-transmit, Horizontal-receive polarization
HK, HKTM	Housekeeping Telemetry

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HDF5	Hierarchical Data Format version 5
HV	Horizontal-transmit, Vertical-receive polarization
ICU	Integrated Correlation Unit
InSAR	Interferometric Synthetic Aperture Radar
ISCE	InSAR Scientific Computing Environment
ISCE3	InSAR Scientific Computing Environment Enhanced Edition (for NISAR)
ISO	International Organization for Standardization
ISRO	Indian Space Research Organisation (British spelling)
JPL	Jet Propulsion Laboratory
JSON	JavaScript Notation
L0B	Level-0B (data)
L1	Level-1 (data)
L2	Level-2 (data)
L3	Level-3 (data)
LRR	[JPL] Limited Release Request
LRS	[JPL] Limited Release System
LUT	Lookup Table
Mbps	Megabits per second
MHz	Megahertz
MOE	Medium-precision Orbit Ephemeris
NASA	National Aeronautics and Space Administration
NETCDF4	Network Common Data Format 4 (also netCDF4)
NISAR	NASA-ISRO Synthetic Aperture Radar
NOE	Near-Realtime Orbit Ephemeris
OpenMP	Open Multi-Processing
PCM	Process Control Management
PDF	Portable Document Format (often pdf)
PDR	Preliminary Design Review
POD	Precision Orbit Determination
POE	Precision Orbit Ephemeris
PRF	Pulse Repetition Frequency
QA	Quality Assurance
R#.#	Release #.# (.0 often not used)
REE	Radar Echo Emulator
RFI	Radio Frequency Interference
RIFG	Range-Doppler Interferogram (L1_RIFG)
ROFF	Range-Doppler Pixel Offsets (L1_ROFF)
RRSD	Raw Radar Signal Data
RRST	Raw Radar Signal Telemetry
RSLC	Range-Doppler Single Look Complex (L1_RSLC)
RTC	Radiometric Terrain Correction
RUNW	Range-Doppler UnWrapped Interferogram (L1_RUNW)
RV	Right-circular, V-receive compact polarization

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SAR	Synthetic Aperture Radar (L-SAR: L-band. S-SAR: S-band)
SAS	Science Algorithm Software
SDS	Science Data System
SDT	Science Definition Team
SIS	Software Interface Specification
SLC	Single Look Complex
SME2	Soil Moisture product based on a 200-meter global EASE Grid projection
SMAP	Soil Moisture Active Passive (Mission)
SNAPHU	Statistical-cost, Network-flow Algorithm for Phase Unwrapping
SRTM	Shuttle Radar Topography Mission
ST	Science Team
SWST	Sampling Window Start Time
TAI	International Atomic Time (Temps Atomique International)
TCF	Terrain Correction Factor
TEC	Total Electron Content
TFdb	Trackframe Database
SWST	Sampling Window Start Time
UR	Urgent Response
UTC	Universal Time Coordinated
UTM	Universal Transverse Mercator
VH	Vertical-transmit, Horizontal-receive polarization
VV	Vertical-transmit, Vertical-receive polarization
WGS84	World Geodetic System 84
XML	eXtensible Markup Language (xml in code)
YAML	YAML Ain't Markup Language

## APPENDIX B: GEOCODED PRODUCT GRIDS

NISAR L2 products will be generated on a pre-defined Track/Frame system. The projection system for a particular frame will be available to the users as a predefined map and will be held constant through the life of the system. Each L2 HDF5 granule itself will include information indicating the projection used for the product.

### Map Projections

The NISAR SDS is able to ingest any Digital Elevation Model whose vertical datum represents height above the WGS84 Ellipsoid and the horizontal datum can be represented by an European Petroleum Standards Group (EPSG) code for generating geocoded product. Table 7-1 lists the various projection systems used to output L2 geocoded products.

Table B-1. Projection Systems for NISAR L2 Products

EPSG code	PROJ.4 string	Common Name	Geographical scope
3031	+proj=stere +lat_0=-90 +lat_ts=-71 +lon_0=0 +k=1 +x_0=0 +y_0=0 +datum=WGS84 +units=m +no_defs	Antarctic Polar Stereographic	Antarctica and Southern Hemisphere Sea Ice
3413	+proj=stere +lat_0=90 +lat_ts=70 +lon_0=- 45 +k=1 +x_0=0 +y_0=0 +datum=WGS84 +units=m +no_defs	NSIDC Sea Ice Polar Stereographic North	Greenland and Northern Hemisphere Sea Ice
32601- 32660	+proj=utm +zone=X-32600 +datum=WGS84 +units=m +no_defs	UTM Zone North	Northern Hemisphere Land except Greenland
32701- 32760	+proj=utm +zone=X-32700 +south +datum=WGS84 +units=m +no_defs	UTM Zone South	Southern Hemisphere Land except Antarctica

### Grid Alignment

NISAR L2 products will use a “pixel is area” convention (<http://geotiff.maptools.org/spec/geotiff2.5.html> , “The “PixelIsArea” raster grid space R, which is the default, uses coordinates I and J, with (0,0) denoting the upper-left corner of the image, and increasing I to the right, increasing J down. The first pixel-value fills the square grid cell with the bounds: top-left = (0,0), bottom-right = (1,1)” ).